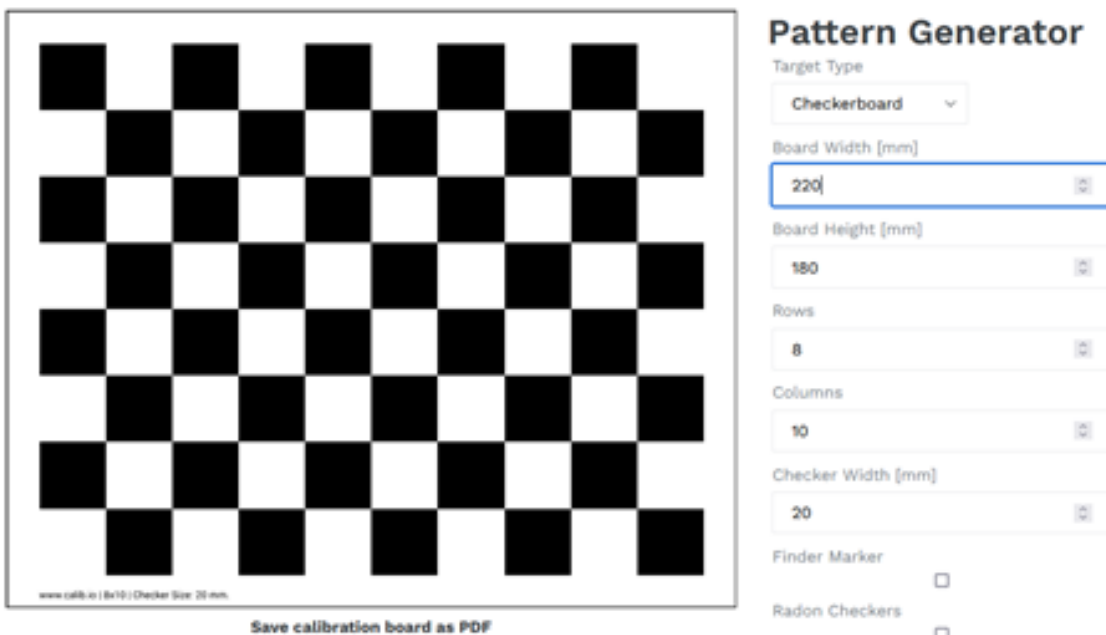


# Calibration de la caméra

[https://docs.nav2.org/tutorials/docs/camera\\_calibration.html](https://docs.nav2.org/tutorials/docs/camera_calibration.html)

- Générer un damier de calibration : 8 x 10 carrés de 20mm
- avec <https://calib.io/pages/camera-calibration-pattern-generator>



- Ce sont les sommets intérieurs des carrés qui sont utilisés, donc 7x9 sommets

## Ressources

- Noeud ROS2 pour Raspberry Cam [https://github.com/christianrauch/camera\\_ros](https://github.com/christianrauch/camera_ros)
- [https://index.ros.org/p/camera\\_ros/](https://index.ros.org/p/camera_ros/)
- <https://medium.com/swlh/raspberry-pi-ros-2-camera-eef8f8b94304>
- 

---

Revision #3

Created 11 October 2024 09:35:22 by admin\_idf

Updated 24 October 2024 12:04:10 by admin\_idf