

Déploiement de ROS2

Docker + VSCode

Quelques conseils de Ragesh (<https://robotair.io/>) que j'ai rencontré au Fraunhofer :

https://github.com/athackst/workstation_setup

<https://docs.ros.org/en/iron/How-To-Guides/Setup-ROS-2-with-VSCode-and-Docker-Container.html>

<https://www.allisonhackston.com/articles/vscode-docker-ros2.html>

Ansible

<https://www.linkedin.com/pulse/deploying-ros2-packages-using-ansible-ragesh-ramachandran/>

<https://blog.robotair.io/best-way-to-ship-your-ros-app-a53927186c35>

https://github.com/swarmBots-ipa/ansible_automation

<https://github.com/ipa-rar/ros2-playbooks>

<https://github.com/Laura7089/ros2-ansible>

https://github.com/jeremyfix/ros2_ansible_turtlebot

<https://github.com/rarraais/ansible-role-ros2>

YOCTO

<https://www.yoctoproject.org/>

Sources

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