

# ROS2

Roomba ROS2

<https://hackaday.io/project/178565-roomba-rpi>

<https://github.com/process1183/roomba-rpi>

<https://github.com/process1183/roomba-ros2>

<https://hackaday.io/project/183524-controll-yer-roomba-600-series-with-esp8266>

CRASHbot, Ubuntu 18 for NVidia Jetson nano, ROS Melodic, AutonomyLab create-robot

<https://www.hackster.io/andrewrgross/crashbot-part-1-planning-a-ros-roomba-helper-robot-d1c8cc>

Roomblock Ubuntu 16 ROS Kinetic

<https://www.instructables.com/Roomblock-a-Platform-for-Learning-ROS-Navigation-W/>

<https://github.com/tork-a/roomblock>

ROS navigation Ubuntu 10

<https://www.ctralie.com/Teaching/DukeDusty2/>

## Ressources

[https://github.com/AutonomyLab/create\\_robot/tree/humble](https://github.com/AutonomyLab/create_robot/tree/humble)

<https://github.com/process1183/roomba-ros2>

<https://github.com/process1183/roomba-rpi>

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